Direct integration method for surface waves on depth dependent flows Yan Li^{*}, Simen Å. Ellingsen



\S I-1 Highlights

- ► A direct numerical method that is
- computationally cheap
- with built-in error estimate
- ▶ of arbitrary accuracy
- \blacktriangleright easily parallelizeable for many values of wave vector **k** .
- Applicable to currents of arbitrary depth dependence
- (Arguably) Preferable to existing numerical methods [1,2] for practical purposes
- Computational cost in the same magnitude as that of existing analytical approximations (c.f. e.g. [3,4])
- ► Full flow field solution with little extra cost

§II Direct integration method



The geometry: a plane wave of wave vector **k** travels atop a horizontal background current of arbitrary depth dependence.

We consider a plane wave with wave vector $\mathbf{k} = [k_x, k_y]$ propagating atop a horizontal current U(z) whose direction and magnitude may vary with depth, running over a flat sea bed of depth h. We seek solutions of a linear wave-current system described by the boundary value problem

$$\begin{split} \bar{w}''(z) - k^2 \bar{w}(z) &= \frac{\mathbf{k} \cdot \mathbf{U}''(z)}{\mathbf{k} \cdot \mathbf{U}(z) - kc} \bar{w}(z); \\ (\mathbf{k} \cdot \mathbf{U}(0) - kc)^2 \bar{w}'(0) - [\mathbf{k} \cdot \mathbf{U}'(0)(\mathbf{k} \cdot \mathbf{U}(0) - kc) + gk^2 + \frac{\sigma k^4}{\rho}] \bar{w}(0) = \\ \bar{w}(0) &= 1; \\ \bar{w}(-h) &= 0, \end{split}$$

in which the prime is the derivative with respect to z, c is the phase velocity, $\bar{w} = \frac{w(\mathbf{k}, z)}{w(\mathbf{k}, 0)}$ (where $w(\mathbf{k}, z)$ is amplitude of the vertical velocity due to wave perturbations) is the unity vertical velocity, g is the gravitational acceleration, ρ is the fluid density, and σ is the surface tension coefficient. Based on Eqs.(1), dispersion relation is obtained

$$D_R(\mathbf{k}, \tilde{c}(\mathbf{k})) \equiv [1 + I_g(\tilde{c}))]\tilde{c}^2 + \tilde{c}\mathbf{k} \cdot \mathbf{U}_0' \tanh kh/k^2 - (g/k + \sigma k/\rho) \tanh kh = 0$$

in which $\tilde{c} = c - \frac{\mathbf{k} \cdot \mathbf{U}(0)}{k}$ and $I_g(\tilde{c}) = \int \mathrm{d}z \frac{\mathbf{k} \cdot \mathbf{U}'' \bar{w}(\mathbf{k}, z) \sinh k(z+h)}{k(\mathbf{k} \cdot \mathbf{U} - \mathbf{k} \cdot \mathbf{U}(0) - k\tilde{c}) \cosh kh}$.

The *direct integration method* uses an iterative approach to solve the linear wave-current system described by the coupled equations (1) and (2) and comes with a built-in error estimate that is introduced in \S III.

$$R(ilde{c}_pprox) \equiv \left|rac{\Delta c}{ ilde{c}_e}
ight| pprox \left|rac{D_R(ilde{c}_pprox)}{ ilde{c}_pproxrac{\partial D_R}{\partial ilde{c}}(ilde{c}_pprox)}
ight|$$

(1a)

(1d)

velocities $u(\mathbf{k}, z)$ and $v(\mathbf{k}, z)$ – is readily obtained by

$$\mathrm{i}k^2ar{p}/
ho = (\mathbf{k}\cdot\mathbf{U}-kc)ar{w}'-\mathbf{k}\cdot\mathbf{U}'ar{w},$$

 $k^2(kc-\mathbf{k}\cdot\mathbf{U})ar{u} = \mathrm{i}k_x[\mathbf{k}\cdot\mathbf{U}'ar{w}-(\mathbf{k}\cdot\mathbf{U}-kc)ar{w}'] - k^2(kc-\mathbf{k}\cdot\mathbf{U})ar{v} = \mathrm{i}k_y[\mathbf{k}\cdot\mathbf{U}'ar{w}-(\mathbf{k}\cdot\mathbf{U}-kc)ar{w}'] - k^2(kc-\mathbf{k}\cdot\mathbf{U})ar{w}' = k^2(kc-\mathbf{k}\cdot\mathbf{U})ar{w} = k^2(kc-\mathbf{k}\cdot\mathbf{U}-kc)ar{w}' = k^2(kc-\mathbf{k}\cdot\mathbf{U}) - k^2(kc-\mathbf{k}\cdot\mathbf{U}) - k^2(kc-\mathbf{k}\cdot\mathbf{U}) - k^2(kc-\mathbf{k}\cdot\mathbf{U}) - k^2(kc-\mathbf{k}\cdot\mathbf{U}) + k^2(kc-\mathbf{k$



(1c)

arbitrary accuracy;

built-in error estimates with little extra cost.





[4] S.Å. Ellingsen & Y. Li, Approximate Dispersion Relations for Waves on Arbitrary Shear Flows. J. Geophys. Res.- Oceans. 122 (2017).