



GENERATIVE DIFFUSION MODELS FOR DOWNSCALING & BIAS CORRECTION OF PRECIPITATION



Michael Aich¹, Philipp Hess^{1,2}, Baoxiang Pan³, Sebastian Bathiany^{1,2}, Yu Huang¹, Niklas Boers^{1,2,4}

I. Motivation

Global warming leads to more intense rainfall events and associated **natural hazards**, e.g. in terms of floods and landslides.

Understanding and accurately **simulating precipitation** is important for adaptation planning and **mitigating damages** associated with climate change.

Earth System Models (ESMs) can simulate precipitation patterns but because they are computationally extremely demanding, we can not resolve small-scale dynamics such as many of the processes relevant to precipitation generation.

Therefore, **ESM fields are biased** compared to observations and their **coarse spatial resolution** prevents accurate projections of extremes.

II. ISSUES WITH STATE-OF-THE-ART

Statistical bias correction (BC) techniques are restricted to single grid cell corrections and produce unrealistic patterns.

Dynamical downscaling (DS) techniques are computationally demanding and require high resolution ESM simulations.

Machine learning (ML) based approaches are hard to train and offer no control over the generative process. Supervised training is not possible because **observations (OBS)** and ESM fields are unpaired.

III. TASK

DS & BC can be formulated as: $\omega = f^{-1} \circ g$

Training a **Diffusion Model (DM)**² to approximate $f^{-1} \approx DM$ allows us to transform fields from $p(ESM)$ to $p(OBS | ESM)$

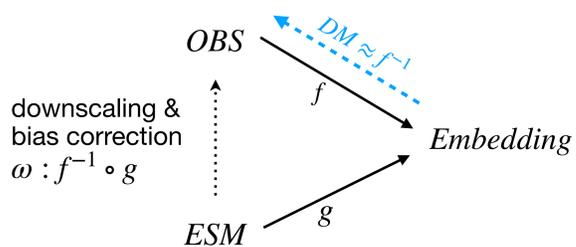


Figure 1: Our downscaling & bias correction framework.

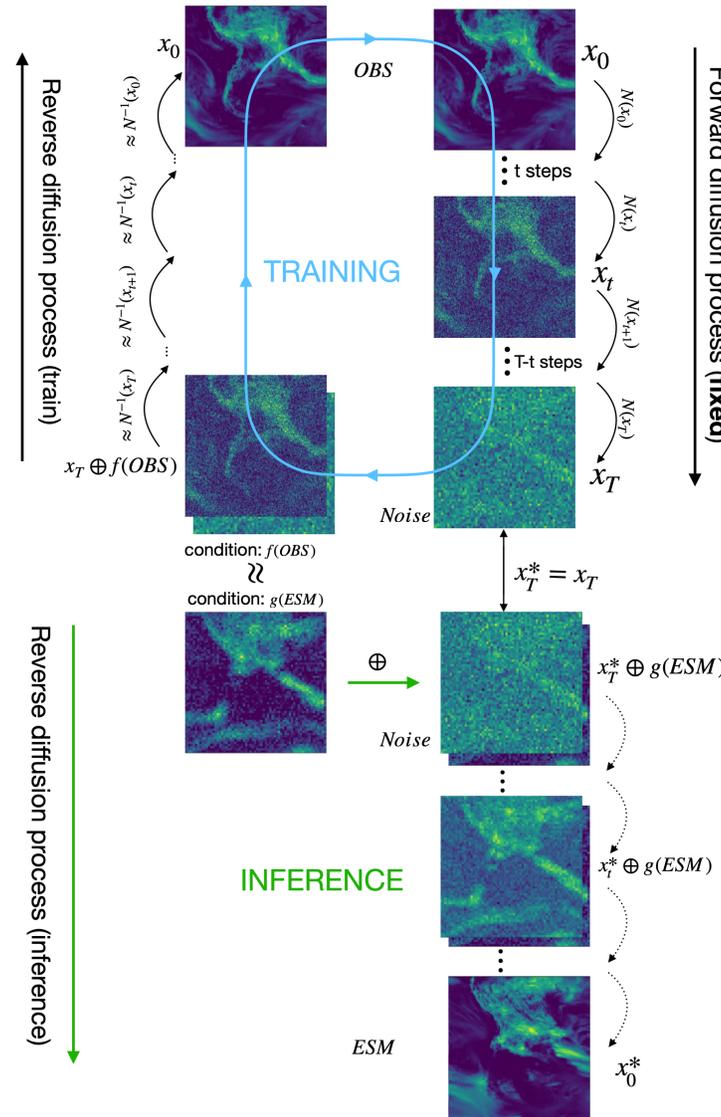


Figure 2: Schematic overview of a conditional diffusion model.

IV. METHODS

Introduce transformations f & g ³ to map OBS & ESM to a shared embedding space

$$f: \mathbf{V}^{obs} \rightarrow \mathbf{V}^{emb}$$

$$g: \mathbf{V}^{esm} \rightarrow \mathbf{V}^{emb}$$

s.t. $f(ERA5)$ is identically distributed to $g(ESM)$

Apply the trained model (**DM**) to ESM fields: $p_{DM}(OBS | g(ESM))$

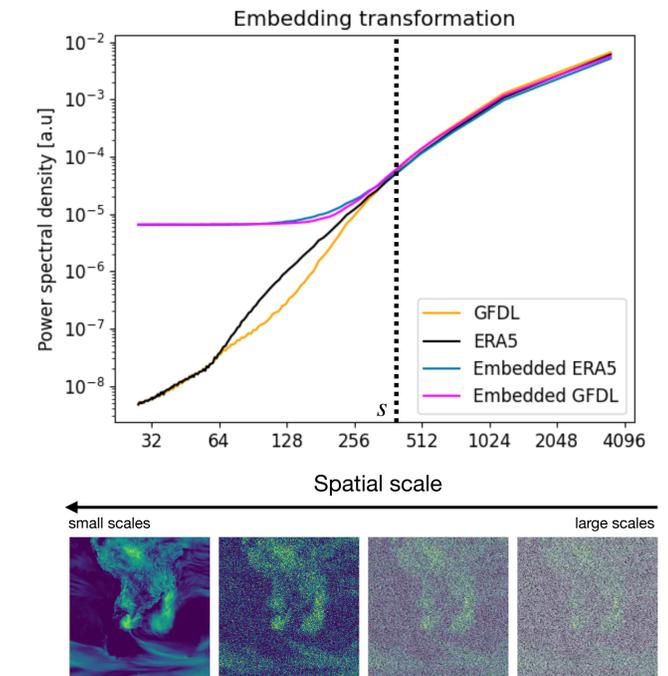


Figure 3: Adding noise to an image destroys a certain amount of information (see PSD). Small amounts of noise destroy small-scale patterns. Increasing the amount of noise will increase the scale up to which patterns are destroyed. The embedding transformations f, g match the PSD's of ERA5 and GFDL. Their PSD's roughly match until a scale s beyond which they diverge. The noise in f, g is chosen to match ERA5 and GFDL in PSD below s .

V. CONTRIBUTION

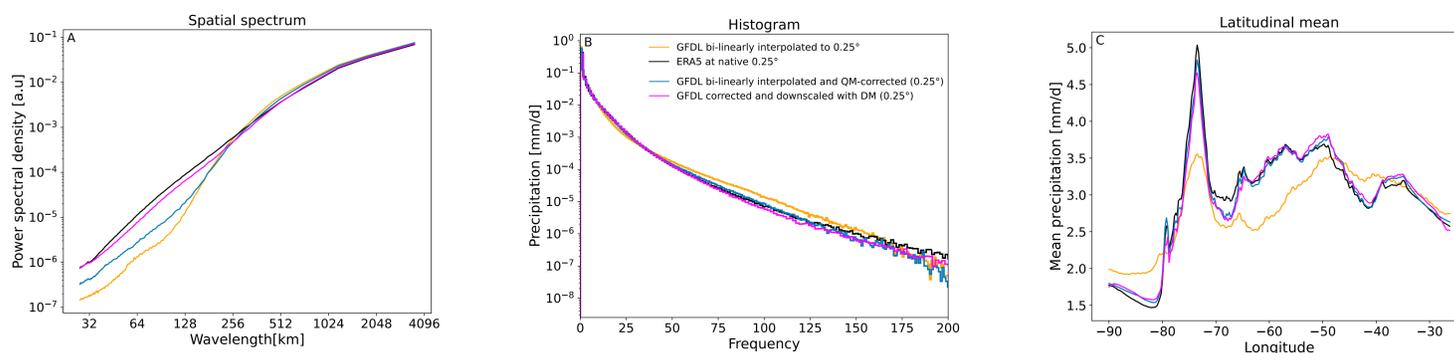


Figure 4: Comparison of ERA5, GFDL, a benchmark and our DM-correction. PSD plot reflects differences in small scale details while latitude profile and histogram indicate statistical bias.

DS^{4A}: DM increases the ESM field resolution from 1° to 0.25°

BC^{4B,4C}: small-scale bias of ESM is corrected: $p_{DM}(OBS | g(ESM)) \approx p(OBS)$

Control: choice up to which scale the ESM should be conserved

Advantages:

- framework¹ is not restricted to a specific DM architecture
- works with **any** ESM
- bias-correction and downscaling done simultaneously
- control over which information to conserve